A chronicle of galaxy mass assembly in the EAGLE simulation

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ABSTRACT
We analyse the mass assembly of central galaxies in the Evolution and Assembly of Galaxies and their Environments (EAGLE) hydrodynamical simulations. We build merger trees to connect galaxies to their progenitors at different redshifts and characterize their assembly histories by focusing on the time when half of the galaxy stellar mass was assembled into the main progenitor. We show that galaxies with stellar mass $M_\star < 10^{10.5}$ $M_\odot$ assemble most of their stellar mass through star formation in the main progenitor ('in situ' star formation). This can be understood as a consequence of the steep rise in star formation efficiency with halo mass for these galaxies. For more massive galaxies, however, an increasing fraction of their stellar mass is formed outside the main progenitor and subsequently accreted. Consequently, while for low-mass galaxies, the assembly time is close to the stellar formation time, the stars in high-mass galaxies typically formed long before half of the present-day stellar mass was assembled into a single object, giving rise to the observed antihierarchical downsizing trend. In a typical present-day $M_\star \geq 10^{11}$ $M_\odot$ galaxy, around 20 per cent of the stellar mass has an external origin. This fraction decreases with increasing redshift. Bearing in mind that mergers only make an important contribution to the stellar mass growth of massive galaxies, we find that the dominant contribution comes from mergers with galaxies of mass greater than one-tenth of the main progenitor’s mass. The galaxy merger fraction derived from our simulations agrees with recent observational estimates.

Key words: galaxies: evolution – galaxies: formation – galaxies: high-redshift – galaxies: interactions – galaxies: stellar content.

1 INTRODUCTION
In the cold dark matter (CDM) cosmological model, the growth of dark matter haloes is largely self-similar, with larger haloes being formed more recently than their low-mass counterparts. The formation and assembly of galaxies are, however, much more complex. Feedback from massive stars and the formation of black holes generates a strongly non-linear relationship between the masses of dark matter haloes and those of the galaxies they host. For low-mass haloes (with mass $\lesssim 10^{11.5}$ $M_\odot$), the stellar mass increases rapidly, with a slope of $\sim 2$, but in higher mass haloes, the stellar mass of the main (or ‘central’) galaxy increases much more slowly than the halo mass, with a slope of $\sim 0.5$ (e.g. Benson et al. 2003; Behroozi, Wechsler & Conroy 2013; Moster, Naab & White 2013). The mass assembly of galaxies will therefore be quite different from those of their parent haloes. Establishing how galaxies assemble their stars over cosmic time is then central to understanding galaxy formation and evolution.

One question we need to answer is the relative importance of the growth of galaxies via internal ongoing star formation ('in situ'), in comparison to the mass contributions of external processes (e.g. Guo & White 2008; Zolotov et al. 2009; Oser et al. 2010; Font et al. 2011; McCarthy et al. 2012; Pillepich, Madau & Mayer 2015). These external processes can be further divided to distinguish between the mass growth due to mergers with galaxies of comparable mass ('major mergers'), and the mass gained from much smaller galaxies ('minor mergers') or barely resolved systems and diffuse...
mass (‘accretion’). While major mergers can rapidly increase a galaxy’s stellar mass, minor mergers are much more common (e.g. Hopkins et al. 2008; Parry, Eke & Frenk 2009).

To evaluate the relative importance of mergers to galaxy assembly, we need to know their merging histories. From an observational perspective, counts of close galaxy pairs (e.g. Williams, Quadri & Franx 2011; Man, Zirm & Toft 2014), or galaxies with disturbed morphologies (e.g. Lotz et al. 2008; Conselice, Yang & Bluck 2009; López-Sanjuan et al. 2011; Stott et al. 2013), provide a census of galaxy mergers. These values can be further converted into galaxy merger rates through the use of a merger time-scale (e.g. Kitzbichler & White 2008). Unfortunately, those methods have their own limitations: galaxies in close-pairs may not be physically related, and may be chance line-of-sight superpositions; morphological disturbances are not unique to galaxy mergers. For example, clumpy star formation driven by gravitational instability can also foster the formation of galaxies with irregular morphologies (Lotz et al. 2008).

In addition, these methods are sensitive to the merger stage and the mass ratio of the merging galaxies. Due to these limitations, the scatter between merger rate measurements is large, and it is difficult to make a reliable assessment of the complementary contribution of mergers to galaxy growth. Recently, deep surveys have begun to shed more light on the galaxy merger rate at high redshifts (e.g. Man et al. 2014). Even so, the evolution of the merger rate remains controversial. An alternative approach is to extract the merger rates of galaxies from a model that reproduces the observed abundance of galaxies (and their distribution in mass), and its evolution with redshift, in a full cosmological context.

In the hierarchical structure formation scenario, the assembly of galaxies is believed to be closely related to the formation histories of their parent haloes. The practice of using halo merger histories to understand the build-up of galaxies can be traced back to Bower (1991), Cole (1991), and Kauffmann, White & Guiderdoni (1993). In these pioneering works, the growth of haloes is described by analytical methods. Numerical techniques like N-body numerical simulations can deal more accurately with the gravitational processes underlying the evolution of cosmic structure. The clustering of haloes is tracked, snapshot by snapshot, and stored in a tree form (‘merger tree’). Halo merger trees therefore record, in a direct way, when and how haloes assemble by accreting other building blocks, and are widely used to rebuild galaxy assembly histories (e.g. Kauffmann et al. 1993, 1999; Roukema et al. 1997; Springel et al. 2001).

To compute galaxy merger rates, one possibility is to combine the halo merger trees with a redshift-dependent abundance matching model that statistically assigns galaxies to dark matter haloes (Fakhouri & Ma 2008; Behroozi et al. 2013; Moster et al. 2013). In this fashion, the observed abundance of galaxies can be inverted to estimate the galaxy merger rate as a function of halo mass and redshift. This provides a great deal of insight, but relies on the accuracy of the statistical model. Although appealing because of its close relation to the real data, the approach may miss physical correlations between the merging objects. A preferable approach is therefore to form galaxies within dark matter haloes using a physical galaxy formation model. It is important to note, however, that reliable conclusions can only be obtained if the overall galaxy stellar mass function accurately reproduces observational measurements (Benson et al. 2003; Schaye et al. 2015).

One approach is to use ‘semi-analytic’ models of galaxy formation. By introducing phenomenological descriptions for feedback from star formation and active galactic nuclei (AGN), such models are able to reproduce the observed galaxy stellar mass function (e.g. Bower et al. 2006; Croton et al. 2006, for a recent review, see Knebe et al. 2015). De Lucia et al. (2006) study the assembly of elliptical galaxies in a semi-analytic model based on the model of Croton et al. (2006). They find that stars in massive galaxies (with stellar mass $M_\star \geq 10^{11} \, M_\odot$) are formed earlier ($z \gtrsim 2.5$) but are assembled later (by $z \approx 0.8$). De Lucia & Blaizot (2007) show further that massive members in galaxy clusters assemble through mergers late in the history of the Universe, with half of their present-day mass being in place in their main progenitor by $z \approx 0.5$. In contrast, less massive galaxies undergo relatively few mergers, acquiring only 20 per cent of their final stellar mass from external objects. Parry et al. (2009) study the assembly and morphology of galaxies in the semi-analytic model of Bower et al. (2006). They found many similarities, but also important disagreements, stemming primarily from the differing importance of disc instabilities in the two models. Parry et al. (2009) find that major mergers are not the primary mass contributors to most spheroids except the brightest ellipticals. This, instead, is brought in by minor mergers and disc instabilities. In their model, the majority of ellipticals, and the overwhelming majority of spirals, never experience a major merger.

Semi-analytic studies such as those above give important insights but suffer from the limitations inherent to the approach, for example, the neglect of tidal stripping of infalling satellites and the absence of information about the spatial distribution of stars, as well as being limited by the overall accuracy of the model. Numerical simulations have fewer limitations, and have thus become an alternative useful tool for these studies. Hopkins et al. (2010) compare the galaxy merger rates derived from a variety of analytical models and hydrodynamical simulations. They find that the predicted galaxy merger rates depend strongly on the prescriptions for baryonic physical processes, especially those in satellite galaxies. For example, the lack of strong feedback can result in a difference in predicted merger rates by as much as a factor of 5. Mass ratios used in merger classification also have an impact on merger rate prediction. Using the stellar mass ratio, rather than the halo mass ratio, can result in an order of magnitude change in the derived merger rate.

With rapidly increasing computational power and much progress in modelling physical processes on subgrid scales, cosmological N-body hydrodynamical simulations are increasingly capable of capturing the physics of galaxy formation (e.g. Hopkins et al. 2013; Vogelsberger et al. 2014). The Evolution and Assembly of Galaxies and their Environments (EAGLE) simulation project accurately reproduces the observed properties of galaxies, including their stellar mass, sizes, and formation histories, within a large and representative cosmological volume (Schaye et al. 2015; Furlong et al. 2015a,b). This degree of fidelity makes the EAGLE simulations a powerful tool for understanding and interpreting a wide range of observational measurements. Previous papers have focused on the evolution of the mass function and the size distribution of galaxies (Furlong et al. 2015a,b), the luminosity function and colour diagram (Trayford et al. 2015) and galaxy rotation curves (Schaller et al. 2015a), as well as many aspects of the $\text{H}_\text{i}$ and $\text{H}_\text{II}$ distribution of galaxies (Lagos et al. 2015; Bahé et al. 2016; Crain et al. 2016) in the EAGLE Universe. But none has tracked the assembly of individual galaxies and decipher the underlying mechanisms as yet. As an attempt to shed some light on the issue, in this work, we connect galaxies seen at different redshifts, creating a merger tree that enables us to establish which high-redshift fragments collapse to form which present-day galaxies (and vice versa). In this way, we can quantify the importance of in situ star formation relative to the mass gain from galaxy mergers and diffuse accretion. Throughout the paper, we will focus on the main, or ‘central’,
galaxies, avoiding the complications of environmental processes such as ram pressure stripping and strangulation that suppress star formation and strip stellar mass from satellites. Unless otherwise stated, stellar masses refer to the stellar mass of a galaxy at the redshift of observation, not to the initial mass of stars formed.

The outline of this paper is as follows. In Section 2, we provide a brief overview of the numerical techniques and subgrid physical models employed by the EAGLE simulations, and describe the methodology used to construct merger trees from simulation outputs. We investigate the assembly histories and merger histories of galaxies and discuss the impact of feedback on galaxy mass build-up in Section 3. We compare our results with some previous works in Section 4, and finally summarize in Section 5. The appendices present the detailed criteria we use to define galaxy mergers and show the impacts of our choices of galaxy mass on our results. The cosmological parameters used in this work is from the Planck mission (Planck Collaboration XVI 2014), $\Omega_{\Lambda} = 0.693$, $\Omega_m = 0.307$, $h = 0.677$, $n_s = 0.96$, and $\sigma_8 = 0.829$.

2 EAGLE SIMULATION AND MERGER TREE

2.1 EAGLE simulation

The galaxy samples for this study are selected from the EAGLE simulation suite (Crain et al. 2015; Schaye et al. 2015). The EAGLE simulations follow the evolution (and, where appropriate, the formation) of dark matter, gas, stars, and black holes from redshift $z = 127$ to the present day at $z = 0$. They were carried out with a modified version of the GADGET 3 code (Springel 2005) using a pressure–entropy-based formulation of smoothed particle hydrodynamics method (Hopkins 2013), coupled to several other improvements to the hydrodynamic calculation (Dalla Vecchia, in preparation; Schaye et al. 2015; Schaller et al. 2015b). The simulations include subgrid descriptions for radiative cooling (Wiersma, Schaye & Smith 2009), star formation (Schaye & Dalla Vecchia 2008), multi-element metal enrichment (Wiersma et al. 2009), black hole formation (Rosas-Guevara et al. 2015; Springel, Di Matteo & Hernquist 2005), as well as feedback from massive stars (Dalla Vecchia & Schaye 2012) and AGN (for a complete description, see Schaye et al. 2015). The subgrid models are calibrated using a well-defined set of local observational constraints on the present-day galaxy stellar mass function and galaxy sizes (Crain et al. 2015).

Each simulation outputs 29 snapshots to store particle properties over the redshift range of $0 \leq z \leq 20$. The corresponding time interval between snapshot outputs ranges from ~0.3 to ~1.35 Gyr. The largest EAGLE simulation, hereafter referred to as Ref-L100N1504, employs 1504$^3$ dark matter particles and an initially equal number of gas particles in a periodic cube with side-length 100 comoving Mpc (cMpc) on each side. This setup results in a particle mass of $9.7 \times 10^6 M_\odot$ and $1.81 \times 10^6 M_\odot$ (initial mass) for dark matter and gas particles, respectively. The gravitational force between particles is calculated using a Plummer potential with a softening length set between snapshot outputs ranges from 0.2 times the mean inter-particle spacing (Davis et al. 1985). Other particles (gas, stars and black holes) are assigned to the same FoF group as their nearest linked dark matter neighbours. The gravitationally bound substructures within the FoF groups are identified using the ‘Friends-of-Friends’ (FoF) algorithm with a linking length of 0.2 times the mean inter-particle spacing (Davis et al. 1985). Other particles (gas, stars and black holes) are assigned to the same FoF group as their nearest linked dark matter neighbours. The gravitational force between particles is calculated using a Plummer potential with a softening length set between snapshot outputs ranges from 0.2 times the mean inter-particle spacing (Davis et al. 1985). Other particles (gas, stars and black holes) are assigned to the same FoF group as their nearest linked dark matter neighbours. The gravitationally bound substructures within the FoF groups are identified using the ‘Friends-of-Friends’ (FoF) algorithm with a linking length of 0.2 times the mean inter-particle spacing (Davis et al. 1985).

The formation of galaxies involves physical processes operating on a huge range of scales, from the gravitational forces that drive the formation of large-scale structure on 10–100 Mpc scales, to the processes that lead to the formation of individual stars and black holes on 0.1 pc and smaller scales. Such a dynamic range, $10^9$ in length and perhaps $10^{12}$ in mass, cannot be computed efficiently without the use of subgrid models. Such models are inevitably approximate and uncertain. In EAGLE, we require that the subgrid models are physically plausible, numerically stable, and as simple as possible. The uncertainty in these models introduces parameters whose values must be calibrated by comparison to observational data (Vernon, Goldstein & Bower 2010). We explicitly recognize that these models are approximate and adopt the clear methodology for selecting parameters and validating the model that is described in detail in Schaye et al. (2015) and Crain et al. (2015). The subgrid parameters calibrated by requiring that the model fits three key properties of local galaxies well: the galaxy stellar mass function, the galaxy size – mass relation and the normalization of the black hole mass – galaxy mass relation and that variations of the parameters alter the simulation outcome in predictable ways (Crain et al. 2015). We find that these data sets can be described well with physically plausible values for the subgrid parameters. We then compare the simulation with further observational data to validate the simulation. We find that it describes many aspects of the observed universe well (i.e. within the plausible observational uncertainties), including the evolution of the galaxy stellar mass function and star formation rates (Furlong et al. 2015b), evolution of galaxy colours and luminosity functions (Trayford et al. 2015). It also provides a good match to observed O VI column densities (Rahmati et al. 2016) and molecular content of galaxies (Lagos et al. 2015), as well as a reasonable description of the X-ray luminosities of AGN (Rosas-Guevara et al. 2015). The good agreement with these diverse data sets, especially those distantly related to the calibration data, provides good reason to believe that the simulation provides a good description of the evolution of galaxies in the observed Universe. It can therefore be used to explore galaxy assembly histories in ways that are not accessible to observational studies.

2.2 Halo identification and subhalo merger tree

Building subhalo merger trees from cosmological simulations involves two steps: first, we identify haloes and subhaloes as gravitationally self-bound structures; secondly, we identify the descendants of each subhalo across snapshot outputs and establish the descendant–progenitor relationship over time.

2.2.1 Halo identification

Dark matter structures in the EAGLE simulations are initially identified using the ‘Friends-of-Friends’ (FoF) algorithm with a linking length of 0.2 times the mean inter-particle spacing (Davis et al. 1985). Other particles (gas, stars and black holes) are assigned to the same FoF group as their nearest linked dark matter neighbours. The gravitationally bound substructures within the FoF groups are then identified by the SUBFIND algorithm (Springel et al. 2001; Dolag et al. 2009). Unlike the FoF group finder, SUBFIND considers all species of particle and identifies self-bound subunits within a bound structure which we refer to as ‘subhaloes’. Briefly, the algorithm assigns a mass density at the position of every particle through a kernel interpolation over a certain number of its nearest neighbours. The local minima in the gravitational potential field are the centres of subhalo candidates. The particle membership of the subhaloes is determined by the iso-density contours defined by the density saddle points. Particles are assigned to at most one subhalo. The subhalo with a minimum value of the gravitational potential within an FoF group is defined as the main subhalo of the group. Any particle bound to the group but not assigned to any other subhaloes within the group are assigned to the main subhalo.
2.2.2 Subhalo merger tree

Although they orbit within an FoF group, subhaloes survive as distinct objects for an extended period of time. We therefore use subhaloes as the base units of our merger trees: FoF group merger trees can be rebuilt from subhalo merger trees if required. The first and main step in building the merger tree is to link subhaloes across snapshots. As in Springel et al. (2005), we search the descendant of a subhalo by tracing the most bound particles of the subhalo. We use the D-Trees algorithm (Jiang et al. 2014) to locate the whereabouts of the $N_{\text{link}} = \min(N_{\text{link max}}, \max(f_{\text{frac}}, N, N_{\text{link min}}))$ most bound particles of the subhalo, where $N$ is the total particle number in the subhalo. We use parameters $N_{\text{link min}} = 10, N_{\text{link max}} = 100, f_{\text{frac}} = 0.1$ in the descendant search. The advantages of focusing on the $N_{\text{link}}$ most bound particles are two-fold. On the one hand, D-Trees can identify a descendant even if most particles are stripped away leaving only a dense core. On the other hand, the criterion minimises misprediction of mergers during flyby encounters (Fakhouri & Ma 2008; Genel et al. 2009).

The descendant identification proceeds as follows. For a subhalo $A$ at a given snapshot, any subhalo at the subsequent snapshot that receives at least one particle from $A$ is labelled as a descendant candidate. From those candidates, we pick the one that receives the largest fraction of $A$’s $N_{\text{link max}}$ most bound particles (denoted as $B$) as the descendant of $A$. $A$ is the progenitor of $B$. If $B$ receives a larger fraction of its own $N_{\text{link}}$ most bound particles from $A$ than from any other subhalo at previous snapshot, $A$ is the principal progenitor of $B$. A descendant can have more than one progenitor, but only one principal progenitor. The principal progenitor can be thought of as ‘surviving’ the merger while the other progenitors lose their individual identity.

Subhaloes sometimes exhibit unstable behaviour during mergers, complicating the descendant/progenitor search. When a subhalo passes through the dense core of another subhalo, it may not be identifiable as a separate object at the next snapshot, but will then reappear in a later snapshot. From a single snapshot, there is no way to know whether the subhalo has merged with another subhalo, or has just disappeared temporarily, and we need to search a few snapshots ahead in order to know which case it falls into. In practice, we search up to $N_{\text{desp}} = 5$ consecutive snapshots ahead for the missing descendants. This gives us between one and $N_{\text{desp}}$ descendant candidates. If the subhalo is the principal progenitor of one or more candidates, the earliest candidate that does not have a principal progenitor is chosen to be the descendant. If there is no such candidate, then the earliest one will be chosen. If the subhalo is not the principal progenitor of any candidates, it will be considered to have merged with another subhalo and no longer appears as an identifiable object.

Occasionally, two subhaloes enter into a competition for bound particles. This occurs as the participants orbit each other prior to merging. In SUBFIND, the influence of a subhalo is based on its gravitational potential well. When two subhaloes are close to each other, their volumes of influence become intertwined and the definition of the main halo may become unclear. For example, when a satellite subhalo orbits closely to its primary host, the satellite can be tidally compressed at some stage and become denser than the host. At this point, the satellite may be classified as the central object of the halo so that most of the halo particles are assigned to it. At a later time, the original central, however, can surpass the satellite in density and reclaim the halo particles. This contest can last for several successive snapshots, accompanied by a see-saw exchange of their physical properties during the merging. Fig. 1 shows an example in which merging haloes take turns to be classified as the central host during the merging process. Overall, fewer than 5 per cent of subhalo mergers in the EAGLE simulations exhibit this behaviour, compatible with the statistics found by Wetzel, Cohn & White (2009). The fact that a fierce contest between subhaloes is sometimes seen during the merging process highlights the inherent difficulties in appropriately describing subhalo properties at that stage.

The property exchanges during such periods are not physical, but rather stem from the requirement that particles be assigned to a unique subhalo on the basis of the spatial coordinates and the local density field in a single snapshot. The history of an object is, however, conveniently simplified by modifying the definition of the most massive progenitor to account for its mass in earlier snapshots. We refer to this progenitor as the ‘main progenitor’, and the branch they stay on in the object’s merger tree as the ‘main branch’. Because of the mass exchange discussed above, we track the main branch using the ‘branch mass’, the sum of the mass over all particle species of all progenitors on the same branch (De Lucia & Blaizot 2007). The main progenitor is then the progenitor that has the maximum branch mass among its contemporaries. This can avoid the misidentification of main progenitors due to the property exchanges occurring for merging subhaloes as we see in Fig. 1. It is worth noting that according to this definition, a lower mass progenitor which has existed for a long time can sometimes be preferred over a more massive progenitor which has formed quickly, when locating main progenitors.

The subhalo merger trees derived by the method described above are publicly available through an SQL data base1 similar to that used for the Millennium simulations (see McAlpine et al. 2016, for more details).

\begin{figure}
\centering
\includegraphics[width=\textwidth]{merger_tree.png}
\caption{A section of a subhalo merger tree illustrating how subhaloes following branches A and B exchange particles before merging. The colour of the solid symbol reflects the halo mass, while the size of the circle represents the ‘branch mass’, which is the sum of the total mass of all the progenitors sitting on the same branch. A see-saw behaviour is clearly seen in the evolution of the halo mass, which may confuse identification of the most important branch. Instead, we use branch mass to locate the main branch of the tree. In this plot, branch A has the largest branch mass and is therefore chosen as the main branch, even though its progenitors are not always the most massive ones.}
\end{figure}

1 http://www.eaglesim.org
2.3 Galaxy sample, galaxy merger tree, and merger type

In this work, galaxies are identified as the stellar components of the subhaloes. The main subhalo of a FoF halo hosts the ‘central’ galaxy, while other subhaloes within the group host satellite galaxies. We will focus on the central galaxies in our study, avoiding the complications of environmental processes such as ram pressure stripping and strangulation that suppress star formation and strip stellar mass from satellite galaxies (e.g. Wetzel et al. 2013; McGee, Bower & Balogh 2014; Barber et al. 2016).

The stellar mass of a galaxy is measured using a spherical aperture. This gives similar results to the commonly used 2D Petrosian aperture used in observational work, but provides an orientation-independent mass measurement for each galaxy. Previous studies based on the EAGLE simulations adopt an aperture of 30 pkpc to measure galaxy stellar mass (e.g. Furlong et al. 2015b; Schaye et al. 2015). Nevertheless, subhaloes do contain a significant population of diffuse stars, particularly in more massive haloes (Furlong et al. 2015b). Such stars are probably deposited by interactions and tidal stripping, and sometimes observed as low-surface brightness intra-cluster/intragroup light (Theuns & Warren 1997; Zibetti & White 2004; McGee & Balogh 2010). Since the formation of massive galaxies is a particular focus of this paper, we use a larger aperture, with a radius of 100 pkpc, to calculate galaxy mass. Note that this mass does not include the stellar mass of satellites lying within the 100 pkpc aperture. As we will show in Appendix C, this aperture choice has little impact on galaxy properties for galaxies with stellar mass $M_\star < 10^{11} M_\odot$ (see also Schaye et al. 2015).

Unless otherwise stated, the galaxy stellar mass in this work refers to the actual mass of stars in the galaxy at the epoch of ‘observation’. Using actual mass replicates what an ideal observer would measure and directly addresses the question of when the current stellar population of the galaxy was formed/assembled. Nevertheless, we should note that the mass budget of the current stellar population is a combination of two processes: stellar mass gain via star formation, accretion and merging, and mass-loss through stellar evolution processes. However, using the actual stellar mass complicates interpretation of the relative mass contribution from different types of merger events since it depends on the age of the stellar population that is accreted. We therefore use the stellar mass initially formed (‘initial mass’), not the actual stellar mass, to evaluate the contributions from internal and external processes to galaxy assembly. In practice, this distinction has little effect on the results and we show the effect of using initial stellar mass throughout in Appendix B.

2.3.1 Galaxy sample

Our study is based on the formation histories of 62 543 galaxies in the largest EAGLE simulation Ref-L100N1504, spanning a stellar mass range of $10^{9.5} - 10^{12} M_\odot$ over redshift $z = 0$–3. In order to test the robustness of our results to resolution, we also extract 1381 galaxies within the same mass range, as a comparison sample, from the EAGLE simulation Recal-L025N0752 (2 $\times$ 752$^3$ dark matter and gas particles in a 25 cMpc box), which has eight times better mass resolution and the same snapshot frequency as Ref-L100N1504. We use subgrid physical models with parameters recalibrated to the present-day observations, as this provides the best match to the observed galaxy population (see Schaye et al. 2015). In order to study the mass dependence of galaxy assembly, we split our samples into three stellar mass bins: a low-mass bin ($10^{9.5} \leq M_\star < 10^{10.5} M_\odot$), an intermediate-mass bin ($10^{10.5} \leq M_\star < 10^{11} M_\odot$), and a high-mass bin ($10^{11} \leq M_\star < 10^{12} M_\odot$).

2.3.2 Galaxy merger tree

We construct galaxy merger trees by focusing on the stellar component of the subhalo merger trees. Fig. 2 shows such a tree for a galaxy with $M_\star = 1.7 \times 10^{11} M_\odot$ at $z = 0$, together with images of its star distribution highlighting its morphological evolution since $z = 1$. The main branch of the tree is marked by the thick black line. It is important to bear in mind that the identification of the main branch is always based on the branch mass; at any particular epoch, the most massive galaxy progenitor may not lie on the main branch. However, for the reasons described in Section 2.2.2, using the branch mass yields more stable and intuitive results.

Galaxy merger trees appear broadly similar to subhalo merger trees, except that the latter contain more fine branches corresponding to small subhaloes within which no stars have formed. Galaxy trees are also less affected by the mass exchange issue than subhalo trees, as star particles are more spatially concentrated.

2.3.3 Merger type

The effects of tidal forces and torques during a merger depend on the mass ratio of the merging systems (e.g. Barnes & Hernquist 1992). A merger between a low-mass satellite and a more massive host is generally less violent than a merger between systems of comparable mass, and has a less dramatic impact on the dynamics and morphology of the host. It is therefore useful to classify mergers into different types according to the mass ratio between the two merging systems, $\mu \equiv M_2 / M_1$. For galaxy mergers, $\mu$ is the ratio of stellar masses between two merging galaxies. While for halo mergers, it is the halo mass ratio.

While this is straightforward in semi-analytic models (since galaxies are uniquely defined entities), in numerical simulations (and in nature as well), merging systems experience mass-loss due to tidal stripping throughout the merging process. Our strategy is therefore to choose a separation criterion, $R_{\text{merge}}$, and determine the merger type when the merging systems are separated, for the first time, by that distance or less. For galaxy mergers, we adopt $R_{\text{merge}} = 5 \times R_\text{1/2}$, where $R_\text{1/2}$ is the half-stellar mass radius of the primary galaxy (note that $R_{\text{merge}}$ is not a projected but a 3D separation). The value of $R_{\text{merge}}$ ranges from $\sim 20$ to 200 pkpc in the stellar mass range explored in this work (see Appendix A), and is similar to the projected separation criteria adopted in observational galaxy pair studies. For subhalo mergers, $R_{\text{merge}} = r_{200},$ where $r_{200}$ is the radius of a region around the FoF group of the subhaloes within which the density is 200 times the cosmological critical density. In the rare event that an object is located within the $R_{\text{merge}}$ of more than one other object, it is considered to be the merging companion of the nearest one.

More often than not, the secondary object may have suffered tidal stripping of mass when the merger type is determined due to the finite time sampling of our snapshot outputs. To alleviate the resulting misestimate of the mass ratio, we compare the mass of the merging systems at the start of the merging event with that at the previous snapshot, and use the maximum to calculate the mass ratio $\mu$. In our study, merging events are classified as major mergers if $\mu \geq 1/4$; as minor mergers if $1/4 > \mu \geq 1/10$; and as diffuse accretion, when $\mu < 1/10$. Our major merger definition is different from that of Cole et al. (2000) or De Lucia & Blaizot (2007) who adopt a larger mass ratio $\geq 1/3$, but is similar to more recent studies.
Figure 2. An example of a galaxy merger history. The galaxy has a stellar mass $M_* = 1.7 \times 10^{11} M_\odot$ at redshift $z = 0$. Symbol colours and sizes are logarithmically scaled with stellar mass. The thick solid line marks the main branch. The final galaxy is built from many small progenitors, but most of these contributors have very low mass. We also show images of its stellar mass distribution in a 200 comoving kpc box at a few redshifts. The galaxy shows prominent spiral-like structure at redshift $z = 1$, but then experiences several interactions with other objects, passing through a shell-like phase to transform into an elliptical galaxy at $z = 0$.

(e.g. Rodriguez-Gomez et al. 2015). Mergers with mass ratio $\geq 1/4$ can produce strong asymmetries in the morphology of both merging galaxies, making them easily identifiable in observations (Casteels et al. 2014).

3 RESULTS

3.1 Galaxy formation and assembly time-scales

A simple way to summarize the formation history of a galaxy is to measure the time-scale on which it assembles its mass. As discussed by De Lucia et al. (2006) and Neistein, van den Bosch & Dekel (2006), this can be assessed in two ways. First, we can measure the total stellar mass in all progenitors of the final galaxy as a function of time. This mass increases through star formation. For many purposes, however, it is more relevant to focus on the growth of the main progenitor if we are interested in connecting galaxies identified in observational studies at different epochs. Following De Lucia et al. (2006), we refer to the time-scale by which the total mass of all progenitors has reached half of the stellar mass of the final galaxy as the ‘formation time’, $t_f$. $t_f$ is closely related to the star formation history of the galaxy. The time-scale by which the main progenitor of the final galaxy has assembled that much mass is defined as the ‘assembly time’, $t_a$. Both time-scales are measured in lookback times. If a galaxy forms most of its stars through in situ star formation, it will have $t_i \approx t_a$.

Fig. 3 plots formation time, $t_f$, against assembly time, $t_a$, for galaxies at $z = 0$ in three stellar mass bins. The galaxies occupy different regions in the plot depending on their stellar mass. Low-mass galaxies ($M_* < 10^{10.5} M_\odot$) typically formed their stars 8 Gyr ago. In spite of a large spread, their formation times scatter about the line of $t_a \approx t_f$, implying an in situ origin for their stars. In contrast, the most massive galaxies formed their stars relatively early, $t_f \sim 11$ Gyr, and have $t_a < t_f$ indicating that a fraction of their stars are formed elsewhere and subsequently assembled into the final system. The delay between $t_a$ and $t_f$ is a strong function of galaxy mass, increasing rapidly as the galaxy mass exceeds $10^{11} M_\odot$. This trend agrees well with previous work (e.g. De Lucia et al. 2006; Neistein et al. 2006; Parry et al. 2009). It is also seen in observational data, as a trend referred to as ‘downsizing’, where old stellar populations dominate massive galaxies (Bower, Lucey & Ellis 1992; Cowie et al. 1996; Heavens et al. 2004; Gallazzi et al. 2005) and low-mass galaxies have a more extended period of star formation (Noeske et al. 2007; Leitner 2012). These results hint that most low-mass galaxies that formed at high redshifts do not ‘survive’ to the present day and have merged into more massive galaxies. Indeed, we find that only half of the galaxies with $M_* \sim 10^9$ to $10^{10.5} M_\odot$ at $z = 3$ survive to $z = 0$.
In a ΛCDM universe, dark matter haloes grow in a self-similar manner, with high-mass haloes typically being formed more recently than their low-mass counterparts (Davis et al. 1985; Bardeen et al. 1986). This is confirmed in Fig. 4, which shows the distribution of $t_\text{f}$ as a function of $t_\text{f}$ for the haloes hosting the galaxies of Fig. 3. Points are again coloured by the present-day stellar mass of the galaxies, as in Fig. 3. We see that both time-scales decrease with increasing halo mass, as expected from the hierarchical structure formation scenario. This is entirely the opposite trend to that seen for the galaxies.

This apparent contradiction is the result of AGN feedback being more effective in high-mass haloes (Bower et al. 2006). At low mass, stellar feedback causes the galaxy’s stellar mass to scale with approximately the square of the halo mass, so that the galaxies grow rapidly as the halo mass increases. The stars gained by accretion and merging are dwarfed by the contribution from ongoing star formation. However, once the halo mass exceeds $\sim 10^{11.5} \, M_\odot$, star formation is strongly suppressed by AGN feedback (see Rosas-Guevara et al. 2015, and Bower et al. 2016) and galaxies grow almost exclusively by accretion and mergers. This transition breaks any self-similarity in the hierarchy: although the most massive galaxies assemble late, the stars they contain were formed at much earlier epochs.

The halo assembly and formation times are remarkably close. This occurs because the dominant contribution to halo growth comes from matter which is not yet bound into galaxy-bearing dark matter haloes. Many previous studies have pointed out that in a CDM cosmology, halo growth is driven by a mix of mergers and accretion of matter that has not yet collapsed into identifiable haloes (e.g. Kauffmann & White 1993; Lacey & Cole 1993; Guo & White 2008; Fakhouri & Ma 2010; Genel et al. 2010; Wang et al. 2011). In contrast, stars are only formed efficiently in well-defined massive haloes. This fundamental differences results in the stark contrast between Figs 3 and 4.

### 3.2 The redshift evolution of galaxy formation and assembly times

In previous section, we have shown that the delay between formation time and assembly time can provide some useful hints on how a galaxy assembles its mass. In this section, we use the differences of both time-scales as a tool to examine the assembly history of galaxies at different redshifts.

To quantify the relative difference between the two time-scales, we define a dimensionless parameter,

$$\delta_t \equiv 1 - t_1/t_2.$$  

Fig. 5 shows the distribution of $\delta_t$ for galaxies at redshift $z = 0–3$. As before, these galaxies are split into three stellar mass bins. We show results for Ref-L100N1504 (solid lines), as well as for the higher resolution (but smaller volume) simulation Recal-L025N0752 (dashed lines) in order to demonstrate the convergence of the results. The shaded region represents the 25th–75th percentiles of the $\delta_t$ distribution. While low-mass galaxies have median $\delta_t < 0.1$ at all redshifts, high-mass galaxies have median $\delta_t$ decreasing with increasing redshift, showing that stellar accretion loses ground to in situ star formation. The same redshift dependence is also found in semi-analytic studies (e.g. Guo & White 2008). This evolution

![Figure 3](image3.png)

**Figure 3.** The formation time, $t_1$, as a function of assembly time, $t_2$, for galaxies at $z \sim 0$. Both time-scales are measured as lookback times in Gyr, and the galaxies are classified into three bins of stellar mass by colours. The solid line represents the one to one relation for the two time-scales. Galaxies with stellar mass ($M_*/M_\odot \leq 10^{10.5}$), are distributed along this line, indicating that they assemble most of their stars through in situ star formation. In massive galaxies of $M_*/M_\odot > 10^{11}$, by contrast, $t_2$ lags behind $t_1$, and the galaxies are offset from the $t_2 = t_1$ line, showing the importance of stars formed in other objects and subsequently accreted. The normalized histograms of the $t_1$ and $t_2$ distributions are shown in marginal panels. The mean and the median of the distributions are indicated by the solid and dotted lines, respectively.

![Figure 4](image4.png)

**Figure 4.** Formation and assembly times for the parent dark matter halo of the galaxies shown in Fig 3. Note that haloes are binned by the stellar mass of their central galaxy, but that bins of higher stellar mass correspond to higher mean halo mass. The solid line represents the case where $t_2 = t_1$, as in Fig 3. In contrast to the situation for galaxies, $t_1$ and $t_2$ increase with decreasing stellar mass, demonstrating the hierarchical nature of the mass assembly of dark matter haloes. Note, however, that formation and assembly times are similar regardless of mass, meaning that halo growth is dominated by accretion of diffuse material. The assembly histories of haloes are markedly different from those of the galaxies they contain.
results from the much higher specific star formation rates of high-redshift galaxies due (at least in part) to the higher gas inflow rates and the less efficient AGN feedback of young galaxies.

We should note that both time-scales are calculated using the actual (observed) stellar masses of galaxies, not the stellar masses initially formed. Because using the latter assigns greater weight to old stars and results in earlier formation and assembly times. In practice, however, the change affects the two time-scales in a similar manner (see Appendix B for detailed discussion) and thus does not change the overall result.

### 3.3 The contribution of star formation in external galaxies

Time-scale studies shed light on the manner in which galaxies with different masses at different redshifts aggregate their stars. But they do not explore quantitatively the roles of internal and external processes therein. In this section, we evaluate the relative importance of those processes by their mass contributions to galaxy assembly. To avoid the mass-loss from stellar evolution, we use initial stellar masses in the calculation.

For each of our samples, we first trace back along the main branch of its merger tree to identify when the main progenitor was involved in a merger event (i.e. mass ratio \( \mu \geq 1/10 \)) or accretion (\( \mu < 1/10 \)) events. We consider the stellar mass of the infalling object at the start of the event (i.e. when the merger type is determined) to be the mass contribution of that event, under the assumption that all the stars of the object will be accreted by the primary host. We sum up the mass that a galaxy has acquired from mergers and accretion, and derive the fractional contribution of external processes, \( f_{\text{ext}} \), by comparing this mass to the final galaxy mass. Tidally induced shocks and angular momentum loss during a merging process can trigger bursts of star formation, contributing to galaxy mass build-up. In our calculation, this mass gain is regarded as part of the contribution from \textit{in situ} star formation.

Fig. 6 shows \( f_{\text{ext}} \) of low-, intermediate-, and high-mass galaxies from redshift \( z = 0 \) to 3. Lines show the median values, while the shaded regions represent the 25th–75th percentiles of the distribution. Both results of the reference Ref-L100N1504 (solid lines) and the higher resolution Recal-L025N0752 (dashed lines) simulations are shown in order to demonstrate the convergence of the results. The low-mass galaxies at redshift \( z = 0 \) acquire only a small fraction of their mass from external galaxies. Over the explored redshift range, the median contribution is \( \sim 0.1 \) with very little evolution. In contrast, galaxies in high-mass bin receive the greatest fractional contribution from mergers and accretion in terms of stellar mass gain, with a median of \( \sim 0.19 \) and a 75th percentile of \( \sim 0.39 \). This fraction declines with redshift to \( \sim 0.08 \) at \( z = 2.5 \). Nevertheless, the low values of \( f_{\text{ext}} \) for galaxies of any mass at both low- and high-redshifts highlight the relative importance of \textit{in situ} star formation with respect to external processes to the assembly of galaxies.

#### 3.4 Galaxy merging history

In preceding sections, we explored the relative roles that \textit{in situ} and external star formation play in galaxy mass build-up. In this section, we continue our investigation by exploring the separate contributions of the different external processes in galaxy assembly. According to the mass ratio between the two merging systems (\( \mu = M_2/M_1 \) where \( M_1 > M_2 \)), these processes are divided into major mergers (\( \mu \geq 1/4 \)), minor mergers (\( 1/4 > \mu \geq 1/10 \)), and accretion (\( \mu < 1/10 \)).

##### 3.4.1 Redshift of last major merger

Almost all of our present-day galaxies, irrespective of their stellar mass, have experienced at least one major merger event in their lives. We use the merger trees to determine the redshift, \( z_{\text{last}} \), when they experienced their last major merger. Fig. 7 shows the cumulative distribution of \( z_{\text{last}} \) for galaxies in three stellar mass bins. The most massive galaxies have a very active merging history, with 68 per cent of the population having been involved in a major merger event since \( z = 1.5 \) (a lookback time of 10 Gyr). This fraction declines with decreasing galaxy mass and drops to 41 per cent for intermediate-mass galaxies, and further down to 22 per cent for the least massive galaxies.

Observations of the stellar dynamics of the Milky Way galaxy suggest that no major mergers have occurred in the last 10 Gyr (Ruchti et al. 2015). Our results show that there is no tension between the quiet history of the Milky Way and the CDM paradigm. The Milky Way could easily have been drawn from the \( \sim 60 \) per cent of the population that has not undergone a major merger. The merger history inferred from the fossil record of the Milky Way is therefore not in conflict with those of similar mass galaxies in the EAGLE simulations.

For comparison, Fig. 7 also shows the cumulative distributions of \( z_{\text{last}} \) for the parent subhalo of those galaxies (dashed lines). Note that we refer to the subhalo mergers as the merger events between galaxy-bearing subhaloes. The merger types are determined using the same method as for galaxy mergers (see Section 2.3.3). In sharp contrast to the active merging histories of high-mass galaxies, only 20 per cent of their host subhaloes have undergone a major merger event in the last 10 Gyr. Intermediate- and low-mass galaxies share more similarity with their parent subhaloes. But, even in the...
Figure 6. The initial stellar mass contributions of mergers (i.e. mass ratio $\mu \geq 1/10$) and diffuse accretion ($\mu < 1/10$) for galaxies of different stellar mass, at redshifts $z = 0$–3 in three stellar mass bins (as coloured). Solid and dashed lines represent the median of the distribution in Ref-L100N1504 and Recal-L025N0752, respectively. Our analysis stops at the redshift when fewer than 10 galaxies are available. The shaded regions bracket the 25th and the 75th percentiles of the distributions. External mass contributions increase with galaxy stellar mass but decrease with redshift.

Figure 7. The cumulative distribution of the redshift of the last major merger event ($\mu \geq 1/4$), $z_{\text{last}}$, for present-day galaxies (solid lines) and their parent subhaloes (dashed lines). Galaxies are split into three stellar mass bins as labelled. Only 22 per cent of galaxies with $M_* < 10^{10.5} M_\odot$ have experienced a major merger event at $z < 1.5$. In contrast, 68 per cent of the most massive galaxies have experienced many recent merger events. This mass dependence is not seen in the $z_{\text{last}}$ distribution of their parent subhaloes, which is due to the non-linear dependence of stellar mass on halo mass. While the distribution for major subhalo mergers is similar to that of low-mass galaxies, the subhalo $z_{\text{last}}$ distribution looks more similar to that of high-mass galaxies when minor halo mergers are included (dotted lines).

intermediate-mass bin, very recent major mergers between galaxies outnumber those of subhaloes by about 10 per cent–15 per cent. This comparison highlights the important difference between the merger classification of galaxies and those of subhaloes, especially the massive ones. In the high-mass range, the mild dependence of the stellar mass on halo mass ($M_* \propto M_h^{1/2}$) means that merging galaxies closely matched in mass may have subhaloes of quite different masses. Dotted lines in Fig. 7 show the distribution of $z_{\text{last}}$ for subhaloes when minor halo mergers are also taken into account. As expected, these lines are much more similar to the $z_{\text{last}}$ distribution of major mergers of massive galaxies.

3.4.2 The contributions of major mergers, minor mergers, and accretion

In this section, we continue our investigation of fractional mass contribution in Section 3.3 further to explore the respective contributions from major merger, minor merger and accretion and their dependence on galaxy mass and redshift. As in Section 3.3, the initial stellar masses of galaxies are used in the calculation in order to remove the impact of stellar evolution-induced mass-loss.

As the fractional mass contributions show large scatter due to the wide variety of galaxy merging histories, we calculate the fraction of galaxies receiving at least a given fractional mass contribution from each process. The panels from left to right in Fig. 8 show the cumulative fraction of galaxies at redshift $z = 0$ (solid lines), 1 (dashed lines), and 2 (dotted lines) as a function of the minimum fractional mass contribution from major mergers, minor mergers and accretion, respectively. As before, galaxies are binned into low-(blue), intermediate- (green), and high-mass (red) bins. Low-mass galaxies at redshift $z = 0$ mainly acquire their external masses through accretion, while major mergers are the main contributor for their high-mass counterparts. Around $\sim 61$ per cent of the most massive population acquired more than half of their external mass through major merger events. Parry et al. (2009) arrived at the same conclusion from their analysis of semi-analytic models in the Millennium simulation (see fig. 8 in their work). This shift in behaviour is driven by the shallow dependence of stellar mass on halo mass at high halo masses. Since $M_* \propto M_h^{1/2}$, a wide range of halo mass ratios lead to mergers occurring between galaxies of comparable mass.

Nevertheless, the role of major mergers diminishes with increasing redshift, and at the same time, accretion plays a larger role towards higher redshift. As our results show, at redshift $z = 2$, galaxies of any mass acquired most of their external mass through accretion.

3.4.3 Evolution of the galaxy merger fraction

Observationally, the frequencies of galaxy pairs and morphologically distorted galaxies at different redshifts are commonly used to put constraints on the role of galaxy mergers, especially major mergers, in driving galaxy formation. In this section, we examine the census of galaxy major mergers, with the aim of shedding light on the evolution of galaxy merger fraction.
We search galaxy merger trees for galaxies appearing in pairs at each snapshot. These pairs are subject to selection criteria somewhat similar to those applied to the observational close-pair studies. Any two galaxies are classified as a merging pair if they: are separated by a distance \( \leq R_{\text{merg}} \) (\( R_{\text{merg}} \) is five times the half-stellar mass radius of the primary galaxy, see Section 2.3.3); have a mass ratio \( \mu \geq 1/4 \); share a common future descendant. The last criterion frees our major merger census from the interference of random line-of-sight alignments.

If two galaxies have not finished merging by \( z = 0 \), they will not appear in the same merger tree because they do not have a common descendant. As a result, they will not be considered to be a merger pair. Kitzbichler & White (2008) show that the merging times of galaxy pairs can be very extended, leading to a large fraction of pairs surviving to \( z = 0 \). To include these pairs in the merger fraction calculation, one should go further in time to construct their merging histories after \( z = 0 \). However, as our results show later, neglecting the unfinished pairs has only a trivial impact on the global merger fraction.

We count the number of galaxies that are in pairs. When a galaxy is paired with more than one secondary galaxy, the primary galaxy is counted only once. The galaxy merger fraction is derived by dividing this number by the total number of galaxies at that snapshot. A merger fraction can be converted into a merger rate if we know the merger time-scale. The time intervals between EAGLE snapshot outputs typically ranges from 0.1 to \( \sim 1 \) Gyr and may thus not suffice to derive an accurate estimate of the merger rate. We therefore focus on the galaxy merger fraction, rather than the merger rate. Our approach is more readily compared to observational measurements (although caution is still warranted because we have not attempted to account for observational biases).

Fig. 9 shows the major merger fraction, \( f_{\text{merge}} \), for galaxies with stellar mass \( M_* \geq 10^{9.5} M_\odot \) (black dots), \( M_* \geq 10^{10.5} M_\odot \) (blue dots), and \( M_* \geq 10^{11} M_\odot \) (red dots) over redshift \( z = 0 \). The galaxy merger fraction increases monotonically towards high redshifts before levelling off at \( z \approx 1 \), depending on mass. The \( f_{\text{merge}} \) of galaxies with \( M_* \geq 10^{11} M_\odot \) even declines for \( z > 2 \). We compare the simulation predictions with a compilation of real data from both galaxy close-pair studies (open symbols; Kartaltepe et al. 2007; Lin et al. 2008; Ryan et al. 2008; De Ravel et al. 2009; Williams et al. 2011; Man et al. 2014) and galaxy merger studies based on morphological diagnostics (solid symbols) like the CAS fraction. We focus on the galaxy merger fraction in the corresponding stellar mass bins.

Observational studies often parametrize the redshift dependence of the galaxy merger fraction as a power law, \( \alpha (1 + z)^n \), with index \( n = 0 \). However, the rise of the merger fraction beyond redshift \( z \approx 1 \) is not as rapid as it is at \( z < 1 \), especially for massive galaxies. Conselice et al. (2009) show that a combined power-law/exponential function can fit both the steep increase of the observed merger fraction at \( z \sim 0 \) and the plateau beyond. We use a combined fitting function \( a(1 + z)^b e^{c(1 + z)} \) to fit the simulation predictions, in which \( a, b, c \) are free parameters and \( z \) is the redshift. The curves

![Figure 8](image-url)  
Figure 8. The fraction of galaxies as a function of the minimum external stellar mass contributed by major mergers (\( \mu \geq 1/4 \), left-hand panel), minor mergers (\( 1/4 > \mu \geq 1/10 \), middle panel) and accretion (\( \mu < 1/10 \), right-hand panel) at redshift \( z = 0 \) (solid lines), 1 (dashed lines), and 2 (dotted lines). The galaxies are split into three bins of stellar mass coded by colours. While accretion plays a larger role than mergers in terms of the external stellar mass contribution in low- and intermediate-mass galaxies, at low redshift, major mergers dominate the external mass contribution in the most massive galaxies.

![Figure 9](image-url)  
Figure 9. Major merger fraction as a function of redshift for galaxies with \( M_* \geq 10^{9.5} M_\odot \) (black circles), \( \geq 10^{10.5} M_\odot \) (blue circles), and \( M_* \geq 10^{11} M_\odot \) (red circles) derived from Ref-L100N1504. The simulation predictions lie within the scatter of the observational data from both close-pair studies (solid grey symbols) and morphological diagnostics (open grey symbols). Curves represent power-law/exponential fits to the simulated merger fraction in the corresponding stellar mass bins. (Conselice et al. 2009) or the Gini/M20 (Conselice, Rajgor & Myers 2008; Lotz et al. 2008; Stott et al. 2013). These data are mostly for galaxies with \( M_* \geq 10^{10} M_\odot \). Note that this comparison is qualitative since a detailed comparison would require careful reconstruction of the observational criteria. Overall, however, the predicted galaxy merger fraction lies within the scatter of observational data, but is most compatible with studies based on morphological analysis.
in Fig. 9 represent the least-square fitting results in three mass bins. Table 1 lists the best-fitting values of the three parameters and their 1σ uncertainties obtained from the fitting.

The merger diagnostics are also sensitive to merger mass ratios, we also consider the impact on our results of extending the merger mass ratio to a smaller value (μ ≥ 1/10). We find that the merger fraction is elevated by only a factor of 1.5–1.8, on average, by the inclusion of minor merging events, and shows similar trends with redshift.

3.5 The impact of feedback on galaxy mass assembly

So far, we have shown that the assembly of massive galaxies is very different to that of their smaller counterparts. A very interesting question is whether this is due to the feedback from star formation and black hole growth. AGN feedback, for example, is able to efficiently suppress in situ star formation by heating the hot coronae of galaxies and suppressing the inflow of cool gas (Bower et al. 2016). To gain more insight on this aspect, we calculate the mass contribution of internal and external processes in simulations with varying efficiencies of feedback from stars and AGN. These runs differ in simulation volume but have the same resolution. Table 2 lists the values of the parameters used in their feedback models. The effect of these changes on the stellar mass function and galaxy star formation rates is considered in Crain et al. (2015).

The panels from left to right in Fig. 10 compare the fractional mass contribution from mergers and accretion, f\text{ext}, for low-, intermediate-, and high-mass galaxies over redshift z = 0–3 in the presence of weak (dot–dashed lines) and strong (dashed lines) stellar feedback, and no AGN feedback (dotted lines). The results for the reference model (solid lines) are also shown for comparison. The lines show the median of the f\text{ext} distribution and stop at the redshift when fewer than 10 galaxies are available for analysis. We find that stellar feedback has very limited impact on the mass build-up of low-mass galaxies (left-hand panel). Increasing or decreasing the feedback efficiency leads to only ≲5% per cent of changes in their f\text{ext}. In the strong feedback case, the analysis consistently suggests a slight decrease of f\text{ext} as more of the star-forming gas within small galaxies is lost in outflows, reducing their contribution to the stellar mass. The formation of massive galaxies is also strongly suppressed, however, and the small simulation volume (25 cMpc) prevents us reliably determining if there is an increase in f\text{ext} in the few large objects that form. In the case of weak stellar feedback, the efficiency of galaxy formation is similarly increased over a wider range of halo mass, and f\text{ext} changes little in the left-hand panel. In the middle panel, f\text{ext} is lower than the reference simulation (and is more similar to the curve in the left-hand panel). In the absence of effective stellar feedback, AGN feedback has a similar impact in high- and low-mass haloes (Bower et al. 2016) and we expect the differences between the panels to be smaller, as seen.

Galaxies in the first two panels are insensitive to the AGN feedback since (in the reference model) star formation driven outflows oppose the build-up of high gas densities in the central regions (Bower et al. 2016). In contrast, the AGN feedback has a very noticeable impact on the f\text{ext} of their massive counterparts. f\text{ext} declines in the absence of AGN feedback, consistent with the negative impact of AGN feedback on in situ star forming in massive galaxies. This explains many of the differences, but not all of them. For example, for the most massive galaxies, there is still a rapid rise in f\text{ext} to the present day that may be related to the recent cosmological acceleration of the Universe.

4 COMPARISONS TO OTHER WORK

In this work, we focus on the assembly and formation of galaxies. This is a topic that has been extensively studied using N-body simulations and semi-analytic galaxy formation models. Kauffmann, Charlot & White (1996) and De Lucia et al. (2006) already show that the formation time of brightest cluster galaxies is much earlier than their assembly time and Parry et al. (2009) show that with the exception of the brightest galaxies, major mergers are not the primary mechanism by which most galaxies assemble their mass. Our hydrodynamic EAGLE simulations exhibit the same trends and their dynamic range allows us to contrast the formation of the most massive galaxies with that of galaxies similar to the Milky Way. We do not, however, find galaxies with formation and assembly times as large as in De Lucia & Blaizot (2007), who find that galaxies with M > 10^{12} \, M_\odot form 50 per cent of their stars at z ≈ 5; galaxies in our highest mass bin only cover the range of 10^{11}–10^{12} \, M_\odot and form most of their stars at z > 2. Guo & White (2008) compare the contributions from star formation and galaxy mergers to the mass build-up of galaxies using semi-analytical models. In common with our results, they find that major merger play an important role in the growth of galaxies more massive than the Milky Way and that the relative importance of star formation increases towards high redshift. Nevertheless, we disagree with their conclusion about major mergers also dominating

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the growth of high-redshift massive galaxies. Our results show that \textit{in situ} star formation, instead of major mergers, is the dominant contributor to those galaxies.

Lackner et al. (2012) examine galaxy formation and assembly histories in adaptive mesh refinement simulations. Their results show that the accreted fraction has a strong dependence on stellar mass, but their calculations do not include AGN feedback and do not capture the observed break in the galaxy stellar mass function. The importance of feedback can be recognized by looking at zoomed simulations of galaxies similar to the Milky Way. Our results disagree with the high accreted star contributions reported by Oser et al. (2010). This discrepancy is presumably due to the lack of effective feedback at high redshift in their runs, as the \textit{in situ} fraction can be drastically reduced in simulations without any feedback (Hirschmann et al. 2012).

Rodriguez-Gomez et al. (2016) also provide some insight on this topic using the Illustris simulation (Vogelsberger et al. 2014). Similar to our results, they confirm the greater role of mergers and accretion in the mass growth of present-day massive galaxies with \( M_\star > 10^{11} \, M_\odot \) as well as the decreasing importance of these processes with increasing redshift. This similarity supports the robustness of our conclusions to varying subgrid physical models. In particular, we make a comparison between the results with varying feedback efficiencies, shedding light on how stellar and AGN feedback affect the mass build-up of galaxies. Nevertheless, there is also disagreement between our results and that of Rodriguez-Gomez et al. (2016). They highlight the importance of major mergers in contributing to the assembly of low-mass galaxies and high-mass galaxies alike. This contrasts with our results which show that accretion, rather than major mergers, are the main contributors in low-mass galaxies. This discrepancy may be the result of the different methods the two works used for merger type determination. While Rodriguez-Gomez et al. (2016) define the type of a merger event when the secondary galaxy reaches its maximum stellar mass, we determine the merger type when the secondary galaxy is some distance, five times the half-stellar mass radius of the primary galaxy, from the primary host. Unfortunately, the time interval of the EAGLE snapshot outputs is not sufficient to demonstrate that the two methods look at the same merging epoch and classify the mergers in the same way. It is also worth noting that the mass-loss from stellar evolution is taken into account in our mass contribution calculation and that Illustris simulation has a steeper slope to the faint-end galaxy mass function, compared to our simulation and observations. The most fundamental difference may, however, be the implementation of stellar and AGN feedback. These are very different in the simulations, and we have shown that this can lead to significant differences in galaxy assembly histories in Section 3.5. Clearly, this is an interesting avenue for more detailed future investigation.

Moster et al. (2013) and Behroozi et al. (2013) consider the topic from a more observational perspective, using the abundance matching method. They find increasing trends in the fraction of accreted stars with increasing galaxy mass and decreasing redshift that agree closely with our simulations. The consistency between the empirical results and the simulation predictions provides encouraging support both to our results and to the EAGLE simulation runs. Our results show that the mass assembly of galaxies, however, is not simply a reflection of the growth of their parent haloes. Additional physical processes, such as stellar and AGN feedback, make galaxy formation efficiency a strong function of halo mass \( M_\text{h} \). The resulting stellar mass–halo mass relation has a steep slope in low-mass haloes (\( M_\star \propto M_\text{h}^{5/3} \)) and a shallower slope at high mass (\( \propto M_\text{h}^{1/2} \)) (e.g. Benson et al. 2003). The steep low-mass slope arises because the binding energy per unit mass of the halo scales with the halo mass as \( M_\text{h}^{5/3} \), while the energy available from stars is proportional to the stellar mass. The high-mass slope arises because AGN feedback is able to suppress star formation and because the cooling time is long in massive haloes (e.g. Rees 1977; Silk & Rees 1998; Benson et al. 2003; Bower et al. 2006; Croton et al. 2006), leaving galaxy merging as the only effective growth channel. From an observational perspective, the connection can be derived by matching the abundance of galaxies and haloes assuming a monotonic relation (e.g. Kravtsov et al. 2004). The dark matter mass function is described as a power law (with index \( \sim -1 \)) with only a slow rollover at high mass. In contrast, the galaxy stellar mass function is almost flat at low mass (e.g. Fontana et al. 2006). Matching the two by abundance requires a quadratic dependence of stellar mass on halo mass. At high mass, the galaxy stellar mass function has a sharp break implying that haloes of increasing mass host galaxies of very similar mass.

The discrepancy implied by these transformations makes mapping the merger histories of haloes to those of galaxies non-trivial.
and halo mass-dependent (e.g. Cattaneo et al. 2011). For low-mass galaxies and haloes, a halo merger with a mass ratio 1/4 may correspond (roughly) to a merger between galaxies of mass ~1/16. For massive galaxies, a minor halo merger (between a massive halo and a satellite halo) may actually correspond to a major (almost equal-mass) galaxy merger. In this high-mass regime, assuming a uniform galaxy formation efficiency to derive galaxy merging histories from halo merging histories inevitably underestimates the importance of major galaxy mergers, and overstates the role of minor mergers. Many papers have pointed out the disagreement between the galaxy merger rate and the halo merger rate (e.g. Berrier et al. 2006; Parry et al. 2009; Hopkins et al. 2010; Guo et al. 2011), and here we are able to demonstrate this directly. We compare the times (in redshift, \( z_{\text{last}} \)) when galaxies and their parent subhaloes experience their last major merger events, and find that the \( z_{\text{last}} \) distribution of massive galaxies differs greatly from that of their host subhaloes. The former looks more closely like the \( z_{\text{last}} \) distribution of subhaloes only when minor subhalo mergers are also included.

The principal aim of this paper has been to quantify the role of mergers in the formation histories of galaxies in the EAGLE reference simulation. Since the simulation provides a good description of the galaxy stellar mass function and its evolution, as well as many other aspects of the observable Universe, we make the implicit assumption that the formation histories of the simulated galaxies provide a good approximation to those of galaxies in the real Universe. The long time-scales of galaxy evolution make it impossible to observe the growth of galaxies directly; nevertheless, it may be possible to reconstruct the build-up of one galaxy, the Milky Way, from careful archaeology of its stellar content, and their the use of chemical tagging techniques (Hogg et al. 2016). Unfortunately, the formation history of galaxies like the Milky Way is extremely diverse, and careful thought will be required to understand how results, such as those from the Gaia satellite, can be used to reach definitive conclusions.

5 SUMMARY AND CONCLUSIONS

In this paper, we have investigated the assembly and merging histories of hundreds of thousands of central galaxies in the EAGLE cosmological simulation project. The hydrodynamic simulations include a range of gas, stellar and black hole physical processes relevant to galaxy formation, and have been shown to match the properties of observed galaxies reasonably well. Because of this, these simulations provide an ideal test bed for elucidating the roles played by galaxy mergers and \textit{in situ} star formation in galaxy formation.

We construct galaxy merger trees by applying the D-Trees algorithm (Jiang et al. 2014) to SUBFIND subhalo catalogues across snapshot outputs. They enable us to chronicle galaxy formation from \( z = 3 \) to the present day. Because galaxies will slowly lose stellar mass due to tidal stripping before they finally merge, a careful definition of the masses of galaxies prior to and during a merger is required. In this paper, we use a definition based on a separation of five times the galaxy half-stellar mass radius to signal the start of a merging event and then determine the merger type. According to the mass ratio between the primary and the secondary galaxies, merger events are classified as either major mergers (with mass ratios \( \mu \geq 1/4 \)), minor mergers (\( 1/4 > \mu \geq 1/10 \)), or accretion (\( \mu < 1/10 \)). Considering that galaxies also suffer mass-loss due to stellar evolution, we use the initial stellar mass, i.e. the stellar mass being formed, when evaluating the relative contributions of \textit{in situ} and external processes to the mass growth of galaxies.

Our main results are summarized as follows.

(i) We contrast the assembly time (\( t_a \), when the main progenitor of a galaxy had assembled half its present-day stellar mass) and the formation time (\( t_f \), when that mass had formed, regardless in which progenitor) of galaxies. Galaxies less massive than \( 10^{10.5} \text{M}_\odot \) have very similar \( t_f \) and \( t_a \), showing that most of their stars formed in their main progenitors. Above a mass of \( 10^{10.5} \text{M}_\odot \), galaxies are dominated by increasingly old stars, but for the most massive galaxies, the assembly time decreases, implying that although the stars are old, they have only recently been assembled into the present-day galaxies (Fig. 3). We also compare the formation and assembly times of galaxies with those of their parent subhaloes and find quite different trends. The \( t_f \) and \( t_a \) of the subhaloes, in contrast, show a high level of similarity over the mass range studied, decreasing monotonically with increasing mass (Fig. 4).

(ii) We quantify the mass fraction of stars that are formed \textit{‘in situ’} versus stars that have an accreted origin. Galaxies less massive than \( 10^{10.5} \text{M}_\odot \) typically acquire less than 10 per cent of their mass through galaxy mergers or accretion of stars formed in other systems. In contrast, in galaxies more massive than \( 10^{11} \text{M}_\odot \), typically \( \sim 20 \) per cent of the system’s stars have an external origin. There is considerable scatter in both cases (Fig. 6).

(iii) The fraction of accreted stellar mass in less massive galaxies evolves mildly with redshift. In the high-mass galaxies, the assembly and formation times become increasingly similar with increasing redshift and the fraction of externally formed stellar mass declines (Figs 5 and 6).

(iv) We measure the distribution of the redshifts when galaxies have their last major mergers. For galaxies less massive than the Milky Way, the median redshift of the last major merger is \( z \approx 2 \), which is compatible with the quiet formation history of the Milky Way implied by recent observations (Fig. 7).

(v) Accretion dominates the external mass contribution for less massive galaxies, while major mergers become the main mass contributor of external mass for massive galaxies (Fig. 8).

(vi) We compute the fraction of galaxies in a snapshot that are undergoing major mergers, and explore the variation of this fraction with redshift and galaxy mass. We find that the merger fraction rises rapidly between the redshifts \( z = 0 \) and 1, but flattens at higher redshift. Given the uncertainties inherent in the comparison, and the range of methods applied to observational data sets to this diagnostic, our simulation predictions display a remarkable similarity with observational studies (Fig. 9).

(vii) Strengthening or weakening stellar feedback results in a decline in the external mass contribution to galaxies. While low-mass galaxies are weakly affected by AGN feedback, their massive counterparts show a significant reduction in the external mass contribution (Fig. 10). These changes can be broadly understood as resulting from changes in the efficiency of ongoing star formation and the impact of AGN feedback.

Overall, we find general agreement between our results and studies based on semi-analytic models. Massive galaxies are found to have started their star formation earlier than low-mass galaxies but partly in objects other than the main progenitor, and then assembled those stars later through mergers and accretion. This assembly history also implies that they have older stellar populations, consistent with the ‘downsizing’ trend seen in many observational studies.

Despite the close relationship between galaxies and their parent haloes, their formation and assembly histories are very different. The formation of dark matter haloes, contrary to that of galaxies,
is typically hierarchical in the sense that their formation times decrease with increasing halo mass. The assembly of haloes also proceeds in a different manner from that of the galaxies that they host. Massive galaxies acquire a fractional mass from major and minor mergers, while their parent haloes grow in mass mainly by smooth accretion.

As in Guo & White (2008), we compare the stellar mass contributions from in situ star formation and external processes to galaxies of various stellar masses and redshifts. These comparisons highlight in situ star formation as the main mechanism in the formation of low- and high-mass galaxies alike at both low and high redshifts. Our investigation also confirms the role of mergers and accretion in the formation of massive galaxies, which has been revealed by many semi-analytic studies (e.g. De Lucia et al. 2006; De Lucia & Blaizot 2007; Guo & White 2008). This result can be attributed to the supermassive black holes developed in these galaxies. Their energetic feedback prevent gas from cooling down to form stars. Massive galaxies, as a result, have no other ways to grow in mass but to accrete stars from other systems. Among all external processes, major mergers contribute most to the addition of external mass to present-day massive galaxies, while accretion is the main contributor for their less massive counterparts. At higher redshift, accretion dominates the external mass contribution for galaxies of any mass. We find both agreements and discrepancies between our results and those of other recent simulations. Some of the discrepancies may result from the different ways in which mergers are identified and their mass contribution are evaluated.

The galaxy merger trees that we construct, and the role of galaxy mergers that we quantify here, will also be used in future work looking at other aspects of the galaxy population. For example, the dependence of galaxy size on merger history is considered as part of Furlong et al. (2015a), and their role in driving colour evolution is considered in Trayford et al. (2016). These works are focused on the observational aspect, while this paper is focused on the underlying physical process. The results we present, of course, come with the caveat that the simulation is not the Universe, and must be understood as applying to an approximation of reality. With future observational facilities, it may become possible to test the results we present directly.

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App. B. Impact of Mass-Loss on the Formation and Assembly Times

We use the actual stellar mass (i.e., the stellar mass observed) of a galaxy to define its formation time, $t_f$, and its assembly time, $t_a$. However, galaxies continuously experience mass-loss due to stellar evolution during their lifetimes (see fig. 1 in Segers et al. 2016). Neglecting this mass-loss in the time-scale calculation would inevitably lead us to an earlier epoch (corresponding to a larger lookback time) to define the $t_f$ and $t_a$. To address the impact, we calculate again the $t_f$ and the $t_a$ of our sample galaxies but using the initial stellar mass (i.e., the mass initially formed). Fig. A1 illustrates the $R_{\text{merge}}$ distribution as a function of the galaxy stellar mass at redshifts $z = 0, 1, 2, 3$. These ranges of values are in a rough accord with the projected separations used in observational galaxy pair studies.

Appendix A: Separation Criteria

The type of a galaxy merger event is determined by the mass ratio between the secondary and the primary galaxies when they are separated by some minimum distance. We do this so that the secondary galaxy is not strongly affected by tidal-induced mass-loss. The separation criterion, $R_{\text{merge}}$, is defined as

$$R_{\text{merge}} = \frac{R_{1/2}}{2},$$

where $R_{1/2}$ is the half-stellar mass radius of the primary galaxy. Note that $R_{\text{merge}}$ is a 3D separation. In this work, we use $R_{\text{merge}}$ as a function of the galaxy stellar mass at redshifts $z = 0, 1, 2, 3$. These ranges of values are in a rough accord with the projected separations used in observational galaxy pair studies.

Figure A1. The characteristic physical separation, $R_{\text{merge}}$, for merging galaxies over the stellar mass and redshift ranges explored in this work. The solid lines represent the means of the distributions, while the error bars depict the 25th and the 75th percentiles. $R_{\text{merge}}$ is defined as five times the half-stellar mass radius of the primary galaxy. The type of a galaxy merger is determined when the two merging galaxies are not less than $R_{\text{merge}}$ apart.

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Figure B1. The median of $\delta_t$ as a function of redshift for galaxies in different mass bins (indicated by colours and legends). The $\delta_t$ is calculated using either initial stellar mass (dashed lines) or actual stellar mass (solid lines). Using initial stellar mass leads to a quantitative change in $\delta_t$ at fixed redshift, especially for massive galaxies, but does not change its evolutionary trend with redshift.

APPENDIX C: EFFECT OF THE APERTURE

In this work, the galaxy mass is defined as the actual (or initial) stellar mass enclosed by a spherical aperture with a galactocentric radius of 100 pkpc (proper kpc). The use of an aperture enables us to focus on the central part of a galaxy where the main properties are derived. Nevertheless, as shown by Schaye et al. (2015), this aperture choice will have an impact on the mass measurement of massive galaxies ($\gtrsim 10^{11} M_\odot$). Compared to their less massive counterparts, massive galaxies usually experience more merging events. Some of their stars may be deposited in the outer regions by the tidal force during a merging process, forming a diffuse and faint intracluster light as observed in the centre of galaxy clusters (e.g. Theuns & Warren 1997; Behroozi et al. 2013). The galaxy mass can be underestimated when an aperture is employed in the mass measurement. For example, we compare the present-day galaxy masses measured using a 100 pkpc aperture to those derived by the SUBFIND algorithm (without an aperture). For low- and intermediate-mass galaxies, there is no difference between the two masses. But for the most massive galaxies, we find that $\sim 30$ per cent of the stellar mass lies outside of the aperture.

To evaluate the mass contributions of external processes to the growth of a galaxy, we sum up the stellar mass that the galaxy has acquired from mergers and accretion and compare it to its final stellar mass. By using an aperture mass, we may underestimate the total stellar mass of a massive galaxy, and thus overestimate the fractional mass contributions of external processes, $f_{ext}$. Fig. C1 compares the distribution of $f_{ext}$ based on a 100 pkpc aperture (solid lines) and no aperture (dashed lines) for galaxies in three stellar mass bins at redshifts $z = 0$–3. Lines represent the medians of the distributions. The shaded regions and dotted lines depict the 25th and the 75th percentiles of the distributions in the 100 pkpc aperture case and no-aperture case, respectively. Using 100 pkpc aperture masses has almost no impact on our results when galaxies are less massive than $\lesssim 10^{11} M_\odot$, and the impact remains small for even more massive galaxies.

Figure B2. Comparisons of the formation time, $t_f$, and the assembly time, $t_a$, that are calculated using actual stellar mass (top panels) and initial stellar mass (bottom panels) for galaxies at $z = 0$. Galaxies are split into three stellar mass bins as indicated by colours and legends. Vertical solid lines indicate the average values of the distributions while the dotted lines the medians.
Figure C1. The fractional mass contribution of mergers and accretion with (solid lines) and without (dashed lines) a 100 pkpc aperture for galaxies at redshifts $z = 0–3$. The galaxies have been split into three stellar mass bins as labelled. Lines represent the medians of the distributions while the shaded regions (dotted lines) mark the 25th and the 75th percentiles.

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